## CHAPTER 3



1

Sw

 $S_B$ 

# General Solution of the Incompressible, Potential Flow Equations

Developing the basic methodology for obtaining the elementary solutions to potential flow problem.

Linear nature of the potential flow problem, the differential equation does not have to be solved individually for flow fields having different geometry at their boundaries.

Instead, the elementary solutions will be distributed in a manner that will satisfy each individual set of geometrical boundary conditions.

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The continuity equation for incompressible and irrotational

$$\nabla^2 \Phi = 0 \qquad (3.1)$$

The velocity component normal to the body's surface and to other solid boundaries must be zero, and in a body-fixed coordinate system

$$\nabla \Phi \cdot \mathbf{n} = 0 \quad (3.2)$$

 $\nabla \Phi$  is measured in a frame of reference attached to the body. The disturbance created by the motion should decay far  $(r \rightarrow \infty)$  from the body

 $\lim_{r \to \infty} (\nabla \Phi - \mathbf{v}) = 0 \quad (3.3)$ 

where  $\mathbf{r} = (x, y, z)$  and  $\mathbf{v}$  is the relative velocity between the undisturbed fluid in V and the body (or the velocity at infinity seen by an observer moving with the body).

V



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#### 3.2 The General Solution, 3D (Continue...)



 $-\int_{\text{sphere }\epsilon} \left(\frac{1}{r}\frac{\partial\Phi}{\partial r} + \frac{\Phi}{r^2}\right) dS + \int_{S} \left(\frac{1}{r}\nabla\Phi - \Phi\nabla\frac{1}{r}\right) \cdot \mathbf{n} \, dS = 0 \quad (3.6b)$ 

 $\int dS = 4\pi \epsilon^2$ (where  $r = \epsilon$ )
Potential and its derivatives are well-behaved functions and therefore do not vary much in the small sphere

$$-\int_{\text{sphere }\epsilon} \left(\frac{\Phi}{r^2}\right) dS = -4\pi \,\Phi(P)$$

Eq. (3.6b) 
$$\longrightarrow \Phi(P) = \frac{1}{4\pi} \int_{S} \left( \frac{1}{r} \nabla \Phi - \Phi \nabla \frac{1}{r} \right) \cdot \mathbf{n} \, dS$$
 (3.7)

This formula gives the value of  $\Phi(P)$  at any point in the flow, within the region V, in terms of the values of  $\phi$  and  $\partial \phi / \partial n$  on the boundaries S

#### 3.2 The General Solution, 3D (Continue...)

Case III: Point P lies on the boundary  $S_{B}$ 

Integration around the hemisphere with radius  $\epsilon$ 

Eq. (3.7) 
$$\longrightarrow \Phi(P) = \frac{1}{2\pi} \int_{S} \left( \frac{1}{r} \nabla \Phi - \Phi \nabla \frac{1}{r} \right) \cdot \mathbf{n} \, dS \quad (3.7a)$$

Flow of interest occurs inside the boundary of  $S_B$  $\mathcal{O}_i$ : internal potential For this flow the point *P* (which is in the region *V*) is exterior to  $S_B$ 

Eq. (3.6) 
$$\longrightarrow 0 = \frac{1}{4\pi} \int_{S_B} \left( \frac{1}{r} \nabla \Phi_i - \Phi_i \nabla \frac{1}{r} \right) \cdot \mathbf{n} \, dS \quad (3.7b)$$

**n** points outward from  $S_B$ 

′S∞

v

#### 3.2 The General Solution, 3D (Continue...)

Combination of Inner and outer Potential

Eq. (3.7) + Eq. (3.7b) 
$$\Phi(P) = \frac{1}{4\pi} \int_{S_B} \left[ \frac{1}{r} \nabla (\Phi - \Phi_i) - (\Phi - \Phi_i) \nabla \frac{1}{r} \right] \cdot \mathbf{n} \, dS$$
$$+ \frac{1}{4\pi} \int_{S_W + S_\infty} \left( \frac{1}{r} \nabla \Phi - \Phi \nabla \frac{1}{r} \right) \cdot \mathbf{n} \, dS$$
(3.8)

The contribution of the  $S_{\infty}$ 

$$\Phi_{\infty}(P) = \frac{1}{4\pi} \int_{S_{\infty}} \left( \frac{1}{r} \nabla \Phi - \Phi \nabla \frac{1}{r} \right) \cdot \mathbf{n} \, dS \quad (3.9)$$

This potential depends on the selection of the coordinate sys. for example, in an inertial system where the body moves through an otherwise stationary fluid  $\Phi_{\infty}$  =Constant

the wake surface is assumed to be thin, such that  $\partial \Phi / \partial n$  is continuous across it (which means that no fluid-dynamic loads will be supported by the wake)

$$\Phi(P) = \frac{1}{4\pi} \int_{S_B} \left[ \frac{1}{r} \nabla (\Phi - \Phi_i) - (\Phi - \Phi_i) \nabla \frac{1}{r} \right] \cdot \mathbf{n} \, dS$$
  
$$- \frac{1}{4\pi} \int_{S_W} \Phi \mathbf{n} \cdot \nabla \frac{1}{r} dS + \Phi_{\infty}(P)$$
(3.10)



#### 3.2 The General Solution, 3D (Continue...)





Doublet strength  $\mu$  is potential difference between the upper and lower wake surfaces (that is, if the wake thickness is zero, then  $\mu = -\Delta \Phi$  on S<sub>w</sub>)

3.2 The General Solution, 3D (Continue...)

Eq. (3.13)   

$$\Phi(P) = -\frac{1}{4\pi} \int_{S_B} \left[ \sigma\left(\frac{1}{r}\right) - \mu \frac{\partial}{\partial n} \left(\frac{1}{r}\right) \right] dS + \frac{1}{4\pi} \int_{S_W} \left[ \mu \frac{\partial}{\partial n} \left(\frac{1}{r}\right) \right] dS + \Phi_{\infty}(P) \quad (3.13a)$$

Source and doublet solutions decay as  $r \rightarrow \infty$  and automatically fulfill the boundary condition of Eq. (3.3) (where **v** is the velocity due to  $\Phi_{\infty}$ )



In Eq. (3.13) non-unique combination of sources and doublets for a particular problem Choice based on the physics of the problem

$$\frac{\partial \Phi_i}{\partial n} = \frac{\partial \Phi}{\partial n} \qquad \text{on} \quad S_B \xrightarrow{\text{source term on } S_B \text{ vanishes and only the doublet distribution remains}}$$

$$\Phi_i = \Phi$$
 on  $S_B$  — doublet term on  $S_B$  vanishes

#### 3.2 The General Solution, 2D (Continue...)



In the two-dimensional case

$$\Phi_1 = \ln r \qquad \text{and} \quad \Phi_2 = \Phi \quad (3.14)$$

Source Potential

Eq. (3.6b) 
$$-\int_{\text{circle }\epsilon} \left( \ln r \frac{\partial \Phi}{\partial r} - \Phi \frac{1}{r} \right) dS + \int_{S} \left( \ln r \nabla \Phi - \Phi \nabla \ln r \right) \cdot \mathbf{n} \, dS = 0 \quad (3.15)$$

Eq. (3.7) 
$$\rightarrow \Phi(P) = -\frac{1}{2\pi} \int_{S} (\ln r \nabla \Phi - \Phi \nabla \ln r) \cdot \mathbf{n} \, dS$$
 (3.16)  
Note:  $\partial/\partial n$  is the orientation of the

If the point *P* lies on the boundary  $S_{B}$ 

$$\Phi(P) = -\frac{1}{\pi} \int_{S} (\ln r \nabla \Phi - \Phi \nabla \ln r) \cdot \mathbf{n} \, dS \quad (3.16a)$$

If the point *P* is inside  $S_B$ 

Eq. (3.7b) 
$$0 = -\frac{1}{2\pi} \int_{S_B} (\ln r \nabla \Phi_i - \Phi_i \nabla \ln r) \cdot \mathbf{n} \, dS \quad (3.16b)$$

Eq. (3.13a)

$$\Phi(P) = \frac{1}{2\pi} \int_{S_B} \left[ \sigma \ln r - \mu \frac{\partial}{\partial n} (\ln r) \right] dS - \frac{1}{2\pi} \int_{S_W} \mu \frac{\partial}{\partial n} (\ln r) dS + \Phi_{\infty}(P) \quad (3.17)$$

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doublet as will be illustrated in later and that the wake model  $S_W$  in the steady, two-dimensional lifting case is needed to represent a discontinuity in

the potential  $\Phi$ 

#### 3.3 Summary: Methodology of Solution



#### 3.4 Basic Solution: Point Source 3D

One of the two basic solutions presented in Eq. (3.13)

Point source element placed at the origin of a spherical coordinate system

$$\Phi = -\frac{\sigma}{4\pi r} \quad (3.19)$$

Velocity field with a radial component only

$$\mathbf{q} = -\frac{\sigma}{4\pi} \nabla \left(\frac{1}{r}\right) = \frac{\sigma}{4\pi} \frac{\mathbf{e}_r}{r^2} = \frac{\sigma}{4\pi} \frac{\mathbf{r}}{r^3} \qquad (3.20)$$

$$(q_r, q_\theta, q_\varphi) = \left(\frac{\partial \Phi}{\partial r}, 0, 0\right) = \left(\frac{\sigma}{4\pi r^2}, 0, 0\right)$$
 (3.21)

Velocity in the radial direction decays with the rate of  $1/r^2$  and is singular at r = 0



#### 3.4 Basic Solution: Point Source 3D (Continue)

The volumetric flow rate through a spherical surface of radius *r* 

$$q_r 4\pi r^2 = \left(\frac{\sigma}{4\pi r^2}\right) \cdot 4\pi r^2 = \sigma$$

positive  $\sigma$  : Source

 $\sigma$  : Volumetric rate

negative  $\sigma$ : Sink



**Note:** this introduction of fluid at the source violates the conservation of mass; therefore, this point must be excluded from the region of solution

If the point element is located at a point  ${\bf r_0}$ 

$$\Phi = \frac{-\sigma}{4\pi |\mathbf{r} - \mathbf{r}_0|} \quad (3.22)$$
$$\mathbf{q} = \frac{\sigma}{4\pi} \frac{\mathbf{r} - \mathbf{r}_0}{|\mathbf{r} - \mathbf{r}_0|^3} \quad (3.23)$$

#### 3.4 Basic Solution: Point Source 3D (Continue)



The Cartesian form

$$\Phi(x, y, z) = \frac{-\sigma}{4\pi\sqrt{(x - x_0)^2 + (y - y_0)^2 + (z - z_0)^2}}$$
(3.24)

The velocity components

$$u(x, y, z) = \frac{\partial \Phi}{\partial x} = \frac{\sigma(x - x_0)}{4\pi [(x - x_0)^2 + (y - y_0)^2 + (z - z_0)^2]^{3/2}}$$
(3.25*a*)

$$v(x, y, z) = \frac{\partial \Phi}{\partial y} = \frac{\sigma(y - y_0)}{4\pi [(x - x_0)^2 + (y - y_0)^2 + (z - z_0)^2]^{3/2}}$$
(3.25b)

$$w(x, y, z) = \frac{\partial \Phi}{\partial z} = \frac{\sigma(z - z_0)}{4\pi [(x - x_0)^2 + (y - y_0)^2 + (z - z_0)^2]^{3/2}}$$
(3.25c)



Collocation points, I

Wake panels

Surface panel

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#### 3.4 Basic Solution: Point Source 3D (Continue)

The basic point element (Eq. (3.24)) can be integrated over a line *I*, a surface *S*, or a volume *V* to create corresponding singularity elements

$$\Phi(x, y, z) = \frac{-1}{4\pi} \int_{l} \frac{\sigma(x_0, y_0, z_0) dl}{\sqrt{(x - x_0)^2 + (y - y_0)^2 + (z - z_0)^2}}$$
(3.26)

$$\Phi(x, y, z) = \frac{-1}{4\pi} \int_{S} \frac{\sigma(x_0, y_0, z_0) \, dS}{\sqrt{(x - x_0)^2 + (y - y_0)^2 + (z - z_0)^2}}$$
(3.27)

$$\Phi(x, y, z) = \frac{-1}{4\pi} \int_{V} \frac{\sigma(x_0, y_0, z_0) \, dV}{\sqrt{(x - x_0)^2 + (y - y_0)^2 + (z - z_0)^2}}$$
(3.28)

Note:  $\sigma$  represents the source strength per unit length, area, and volume

The velocity components induced by these distributions can be obtained by differentiating the corresponding potentials

$$(u, v, w) = \left(\frac{\partial \Phi}{\partial x}, \frac{\partial \Phi}{\partial y}, \frac{\partial \Phi}{\partial z}\right)$$



#### 3.5 Basic Solution: Point Doublet 3D

The second basic solution, presented in Eq. (3.13), is the doublet

$$\Phi = \frac{\mu}{4\pi} \mathbf{n} \cdot \nabla \left(\frac{1}{r}\right) \quad (3.29)$$

 $\Phi_{\text{doublet}} = -(\partial/\partial n)\Phi_{\text{source}}$  for elements of unit strength

Developing Doublet element from Source element a point sink at the origin and a point source at I

$$\Phi = \frac{\sigma}{4\pi} \left( \frac{1}{|\mathbf{r}|} - \frac{1}{|\mathbf{r} - \mathbf{l}|} \right) \quad (3.30)$$

 $l \rightarrow 0 \& \sigma \rightarrow \infty$  such that  $l\sigma \rightarrow \mu$  ( $\mu$  is finite)

$$\Phi = \lim_{\substack{l \to 0 \\ \sigma \to \infty \\ \sigma l \to \mu}} \frac{\sigma}{4\pi} \left( \frac{|\mathbf{r} - \mathbf{l}| - |\mathbf{r}|}{|\mathbf{r}||\mathbf{r} - \mathbf{l}|} \right)$$



3.5 Basic Solution: Point Doublet 3D (Continue)

As 
$$l \to 0$$

$$\begin{cases} |\mathbf{r}||\mathbf{r} - \mathbf{l}| \to r^2 & \text{Eq. (3.30)} \\ (|\mathbf{r} - \mathbf{l}| - |\mathbf{r}|) \to -l \cos \vartheta & \text{Eq. (3.30)} \end{cases} \Phi = \frac{-\mu}{4\pi} \frac{\cos \vartheta}{r^2} \quad (3.31)$$

The angle  $\vartheta$  is between the unit vector  $\mathbf{e}_i$  pointing in the sink-to-source direction (doublet axis) and the vector  $\mathbf{r}$  P



#### 3.5 Basic Solution: Point Doublet 3D (Continue)



$$\Phi_{\text{doublet}} = \frac{-\mathbf{e}_l \cdot \mathbf{r}}{4\pi r^3} = -\mathbf{e}_l \cdot \nabla \left(\frac{-1}{4\pi r}\right) = -\frac{\partial}{\partial n} \Phi_{\text{source}} \qquad (3.33)$$

For example, for a doublet at the origin and the doublet strength vector ( $\mu$ , 0, 0) aligned with the x axis ( $\mathbf{e}_l = \mathbf{e}_x$  and  $\vartheta = \theta$ ), the potential in spherical coordinates is

$$\Phi(r,\theta,\varphi) = \frac{-\mu\cos\theta}{4\pi r^2} \qquad (3.34)$$

The velocity potential due to such doublet elements, located at  $(x_0, y_0, z_0)$ , is

$$\Phi(x, y, z) = \frac{\mu}{4\pi} n \cdot \nabla \left(\frac{1}{|\mathbf{r} - \mathbf{r}_0|}\right) = \frac{\mu}{4\pi} \frac{\partial}{\partial n} \left(\frac{1}{|\mathbf{r} - \mathbf{r}_0|}\right) \quad (3.35)$$

 $\partial/\partial n$  as the derivative in the direction of the three axes

$$\Phi(x, y, z) = \frac{\mu}{4\pi} \begin{pmatrix} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \\ \frac{\partial}{\partial z} \end{pmatrix} \frac{1}{\sqrt{(x - x_0)^2 + (y - y_0)^2 + (z - z_0)^2}} \quad (3.36)$$



 $r \sin \theta$ 

 $x = r \cos \theta$   $y = r \sin \theta \cos \varphi$  $z = r \sin \theta \sin \varphi$ 

#### 3.5 Basic Solution: Point Doublet 3D (Continue)

Equation (3.34) shows that the doublet element does not have a radial symmetry but rather has a directional property. Therefore, in Cartesian coordinates three elements are defined

$$\Phi(x, y, z) = \frac{-\mu}{4\pi} (x - x_0) [(x - x_0)^2 + (y - y_0)^2 + (z - z_0)^2]^{-3/2}$$
(3.37)

$$\Phi(x, y, z) = \frac{-\mu}{4\pi} (y - y_0) [(x - x_0)^2 + (y - y_0)^2 + (z - z_0)^2]^{-3/2}$$
(3.38)

$$\Phi(x, y, z) = \frac{-\mu}{4\pi} (z - z_0) [(x - x_0)^2 + (y - y_0)^2 + (z - z_0)^2]^{-3/2}$$
(3.39)

The velocity components in spherical coordinates for x- directional point doublet ( $\mu$ , 0, 0)

$$q_r = \frac{\partial \Phi}{\partial r} = \frac{\mu \cos \theta}{2\pi r^3} \qquad (3.40)$$
$$q_\theta = \frac{1}{r} \frac{\partial \Phi}{\partial \theta} = \frac{\mu \sin \theta}{4\pi r^3} \qquad (3.41)$$
$$q_\varphi = \frac{1}{r \sin \theta} \frac{\partial \Phi}{\partial \varphi} = 0 \qquad (3.42)$$



The velocity components in Cartesian coordinates for x- directional point doublet ( $\mu$ , 0, 0)

$$u = -\frac{\mu}{4\pi} \frac{(y - y_0)^2 + (z - z_0)^2 - 2(x - x_0)^2}{[(x - x_0)^2 + (y - y_0)^2 + (z - z_0)^2]^{5/2}} \quad (3.43)$$

Differentiating Eq. (3.37)  
$$v = \frac{3\mu}{4\pi} \frac{(x - x_0)(y - y_0)}{[(x - x_0)^2 + (y - y_0)^2 + (z - z_0)^2]^{5/2}}$$
(3.44)

$$w = \frac{3\mu}{4\pi} \frac{(x - x_0)(z - z_0)}{[(x - x_0)^2 + (y - y_0)^2 + (z - z_0)^2]^{5/2}}$$
(3.45)

This basic point element can be integrated over a line *I*, a surface *S*, or a volume *V* to create the corresponding singularity elements (for  $(\mu, 0, 0)$ )

$$\Phi(x, y, z) = \frac{-1}{4\pi} \int_{l} \frac{\mu(x_0, y_0, z_0) \cdot (x - x_0) dl}{[(x - x_0)^2 + (y - y_0)^2 + (z - z_0)^2]^{3/2}}$$
(3.46)

$$\Phi(x, y, z) = \frac{-1}{4\pi} \int_{S} \frac{\mu(x_0, y_0, z_0) \cdot (x - x_0) \, dS}{[(x - x_0)^2 + (y - y_0)^2 + (z - z_0)^2]^{3/2}}$$
(3.47)

$$\Phi(x, y, z) = \frac{-1}{4\pi} \int_{V} \frac{\mu(x_0, y_0, z_0) \cdot (x - x_0) \, dV}{[(x - x_0)^2 + (y - y_0)^2 + (z - z_0)^2]^{3/2}}$$
(3.48)

3.6 Basic Solution: Polynomials 3D

Laplace's equation  
is a 2<sup>nd</sup> order PDE   
velocity components  

$$u = \frac{\partial \Phi}{\partial x} = A \equiv U_{\infty}, \quad v = \frac{\partial \Phi}{\partial y} = B \equiv V_{\infty}, \quad w = \frac{\partial \Phi}{\partial z} = C \equiv W_{\infty} \quad (3.50)$$

Where  $U_{\omega}$ ,  $V_{\omega}$ , and  $W_{\omega}$  are constant velocity components in the x, y, and z directions. the velocity potential due a constant free-stream flow in the x direction is

 $\Phi = U_{\infty}x \quad (3.51)$ 

and in general

 $\Phi = U_{\infty}x + V_{\infty}y + W_{\infty}z \qquad (3.52)$ 





#### 3.6 Basic Solution: Polynomials 3D (Continue)



Additional polynomial solutions can be sought

 $\Phi = Ax^2 + By^2 + Cz^2 \quad (3.53) \xrightarrow{\text{to satisfy}} \nabla^2 \Phi = A + B + C = 0$ Laplace's Eq

*A, B,* and *C* should be constants. There are numerous combinations of constants that will satisfy this condition.

$$A = -C \rightarrow \Phi = A(x^{2} - z^{2}) \rightarrow \begin{bmatrix} u = 2Ax \\ v = 0 \\ w = -2Az \end{bmatrix}$$
  
Streamline equation (Eq. 1.6a)  
$$\frac{dx}{u} = \frac{dz}{w} \rightarrow \frac{dx}{2Ax} = \frac{dz}{-2Az} \qquad D = -1$$
  
$$xz = \text{ const.} = D \rightarrow \begin{bmatrix} 0 \\ -2Az \end{bmatrix}$$
  
At origin  $x = z = 0$ , velocity components  $u = w = 0$   
stagnation point

**3.7 2D Version of the Basic Solutions (Source)** 

At 3D source  
element 
$$\begin{cases} q_r \neq 0 \\ q_\theta = 0 \\ q_\varphi = 0 \end{cases}$$
At 2D source  
element 
$$\begin{cases} q_r \neq 0 \\ q_\theta = 0 \\ q_\theta = 0 \end{cases}$$
$$\begin{cases} For Irrotational \\ flow \end{cases} \zeta_y = 2\omega_y = -\frac{1}{r} \left[ \frac{\partial}{\partial r} (rq_\theta) - \frac{\partial}{\partial \theta} (q_r) \right] = \frac{1}{r} \frac{\partial}{\partial \theta} (q_r) = 0$$

Satisfing the continuity equation (Eq. (1.35))

$$\nabla \cdot \mathbf{q} = \frac{dq_r}{dr} + \frac{q_r}{r} = \frac{1}{r} \frac{d}{dr} (rq_r) = 0 \qquad \qquad \mathbf{r} q_r = q_r(\mathbf{r})$$

$$rq_r = \text{const.} = \sigma/2\pi$$

 $\sigma$ : area flow rate passing across a circle of radius *r*. velocity components for a source element at the origin:



*q*, function of *r* only

#### 3.7 2D Version of the Basic Solutions (Source)

In Cartesian coordinates with source located at  $(x_o, z_o)$ 

$$\Phi(x, z) = \frac{\sigma}{2\pi} \ln \sqrt{(x - x_0)^2 + (z - z_0)^2} \quad (3.60)$$

$$u = \frac{\partial \Phi}{\partial x} = \frac{\sigma}{2\pi} \frac{x - x_0}{(x - x_0)^2 + (z - z_0)^2} \quad (3.61)$$

$$w = \frac{\partial \Phi}{\partial z} = \frac{\sigma}{2\pi} \frac{z - z_0}{(x - x_0)^2 + (z - z_0)^2} \quad (3.62)$$

In 2D stream fuction Eqs. (2.80a,b)

$$q_{\theta} = -\frac{\partial \Psi}{\partial r} = 0 \qquad (3.63)$$
Integrating
$$\Psi = \frac{\sigma}{2\pi} \theta \qquad (3.65)$$

$$q_{r} = \frac{1}{r} \frac{\partial \Psi}{\partial \theta} = \frac{\sigma}{2\pi r} \qquad (3.64)$$
Integr. const.= zero
$$\Psi = \frac{\sigma}{2\pi} \theta \qquad (3.65)$$
Velocity Potential  $\Phi = \frac{\sigma}{2\pi} \ln r$ 

$$\Psi = \frac{\sigma}{2\pi} \theta \qquad \text{Stream Function}$$

#### 3.7 2D Version of the Basic Solutions (Doulet)

2D doublet can be obtained by a point source and a point sink approach each other

3D Doublet  
Eq. (3.32) 
$$\Phi(r) = \frac{-\mu \cdot \mathbf{r}}{2\pi r^2} \quad (3.66)$$

$$\Phi_{\text{doublet}} = -\frac{\partial}{\partial n} \Phi_{\text{source}} \quad \Phi(r) = -\frac{\partial}{\partial n} \frac{\sigma}{2\pi} \ln r \quad (3.67)$$
Eq. (3.33)

Replacing the source strength by  $\mu$  & with **n** in the x direction  $\mu = (\mu, 0)$ 

Eq. (3.66) 
$$\Phi(r, \theta) = \frac{-\mu}{2\pi} \frac{\cos \theta}{r}$$
 (3.68)

The Velocity field by differentiating the velocity potential

$$q_r = \frac{\partial \Phi}{\partial r} = \frac{\mu \cos \theta}{2\pi r^2} \qquad (3.69)$$
$$q_\theta = \frac{1}{r} \frac{\partial \Phi}{\partial \theta} = \frac{\mu \sin \theta}{2\pi r^2} \qquad (3.70)$$









#### 3.7 2D Version of the Basic Solutions (Doulet)

The velocity potential in Cartesian, doublet at the point ( $x_0$ ,  $z_0$ )

$$\Phi(x,z) = \frac{-\mu}{2\pi} \frac{x - x_0}{(x - x_0)^2 + (z - z_0)^2} \qquad (3.71)$$

The velocity components

$$u = \frac{\mu}{2\pi} \frac{(x - x_0)^2 - (z - z_0)^2}{[(x - x_0)^2 + (z - z_0)^2]^2}$$
(3.72)  
$$\mu = \frac{2(x - x_0)(z - z_0)}{[(x - x_0)(z - z_0)^2]^2}$$

$$w = \frac{\mu}{2\pi} \frac{2(x - x_0)(z - z_0)}{[(x - x_0)^2 + (z - z_0)^2]^2}$$
(3.73)

Deriving the stream function for this doublet element



Streamlines

$$q_{\theta} = -\frac{\partial \Psi}{\partial r} = \frac{\mu \sin \theta}{2\pi r^{2}} \qquad (3.74) \qquad \text{Integrating} \qquad \Psi = \frac{\mu \sin \theta}{2\pi r} \qquad (3.76)$$
$$q_{r} = \frac{1}{r} \frac{\partial \Psi}{\partial \theta} = \frac{\mu \cos \theta}{2\pi r^{2}} \qquad (3.75)$$

Note: a similar doublet element where  $\mu = (0,\mu)$  can be derived by using Eq. (3.66)

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### 3.8 Basic Solution: Vortex

In 2D Point Vortex In 3D Vortex Filament Velocity Field by Biot–Savart Law

A singularity element with only a tangential velocity component Velocity components:

$$q_{r} = 0$$

$$q_{\theta} = q_{\theta}(r, \theta)$$
Substitution in continuity  
equation (Eq. (1.35))
$$q_{\theta} = q_{\theta}(r)$$
For irrotational flow
$$\zeta_{y} = 2\omega_{y} = -\frac{1}{r} \left[ \frac{\partial}{\partial r} (rq_{\theta}) - \frac{\partial}{\partial \theta} (q_{r}) \right] = -\frac{1}{r} \frac{\partial}{\partial r} (rq_{\theta}) = 0$$

$$rq_{\theta} = \text{const.} = A$$
Integrating with respect to r

#### 3.8 Basic Solution: Vortex (Continue)



Calculating A by using the definition of the circulation

$$\Gamma = \oint \mathbf{q} \cdot d\mathbf{l} = \int_{2\pi}^{0} q_{\theta} \cdot r \, d\theta = -2\pi A \longrightarrow A = -\frac{1}{2}$$

Note: Γ is positive in clockwise The velocity field:

$$q_r = 0 \qquad (3.77)$$
$$q_\theta = -\frac{\Gamma}{2\pi r} \quad (3.78)$$

The tangential velocity component decays at a rate of 1/rThe velocity potential for a vortex element at the origin

integration 
$$\Phi = \int q_{\theta} r \, d\theta + C = -\frac{\Gamma}{2\pi}\theta + C \quad (3.79)$$

Integrating around a vortex we do find vorticity concentrated at a zero-area point, but with finite circulation. if we integrate **q** . *dl* around any closed curve in the field (not surrounding the vortex) the value of the integral will be zero.

The vortex is a solution to the Laplace equation and results in an irrotational flow, excluding the vortex point itself.

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#### 3.8 Basic Solution: Vortex (Continue)

In Cartesian coordinates for a vortex located at  $(x_0, z_0)$ 

$$\Phi = -\frac{\Gamma}{2\pi} \tan^{-1} \frac{z - z_0}{x - x_0}$$
(3.80)

$$u = \frac{\Gamma}{2\pi} \frac{z - z_0}{(z - z_0)^2 + (x - x_0)^2} \qquad (3.81)$$

$$w = -\frac{\Gamma}{2\pi} \frac{x - x_0}{(z - z_0)^2 + (x - x_0)^2} \quad (3.82)$$



Deriving stream function for 2D vortex located at the origin, in x-z or  $(r-\theta)$  plane

$$q_{\theta} = -\frac{\partial \Psi}{\partial r} = -\frac{\Gamma}{2\pi r} \quad (3.83)$$

$$q_{r} = \frac{1}{r} \frac{\partial \Psi}{\partial \theta} = 0 \quad (3.84)$$
Integrating
$$\Psi = \frac{\Gamma}{2\pi} \ln r \quad (3.85)$$

The streamlines where  $\Psi$ = const

 $A = -\frac{1}{2\pi}$   $q_{\theta}$   $q_{\theta} = -\frac{\Gamma}{2\pi r}$  r

#### 3.9 Principle of Superposition



If  $\varphi_1, \varphi_2, \ldots, \varphi_n$  are solutions of the Laplace equation, which is linear, then



Where  $c_1, c_2, \ldots, c_n$  are arbitrary constants

This superposition principle is a very important property of the Laplace equation, paving the way for solutions of the flowfield near complex boundaries. In theory, by using a set of elementary solutions, the solution process (of satisfying a set of given boundary conditions) can be reduced to an algebraic search for the right linear combination of these elementary solutions.